

### Hybrid MD/HD modelling

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fields, atoms, scales, etc...

fluctuating hydrodynamic

Coupling the scales

The model

Conservation laws

Constraining the dynamics

Results

2D Lennard-Jones 3D liquid

Conclusions

Modelling solutions of biomolecules at atomistic and continuum representation at the same time: hybrid MD/hydrodynamics framework

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Queen Mary University of London, Aston University, Cambridge University, RIKEN

Multiscale Modelling of Condensed Phase and Biological Systems, 8 Jan 2014

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## The project

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**Title**: 'Using next generation computers and algorithms for modelling the dynamics of large biomolecular systems'

Consortium: 5 groups (Japan, UK, Russia)

**Funding**: G8 Research Councils Initiative on Multilateral Research Funding - Exascale Computing

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## Hybrid MD/HD: motivation

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- **Motivation**: multiphysics/multiscale (speed up and data reduction)
- Examples:
  - bridging atomistic times and microfluidic mixer times (9 orders of magnitude difference),
  - the effects of viscosity and hydrodynamic shear on protein folding.





## multiphysics/multiscale

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AP Markesteijn and SA Karabasov, J. Comput. Phys., 258, 137 (2014)



## Fluctuations in biomolecular systems

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## Water density around dialanine zwitterion



Question: to what extend the dynamics of water density (fluctuations) is connected with the dynamics of the peptide (quantified by its dihedral angles  $\phi$  and  $\psi$ )?



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# Water density correlation with the peptide motion



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Answer: not only connected but strongly correlated at very specific periods, when the conformational transitions occur D Nerukh and S Karabasov, J. Phys. Chem. Lett., 4, 815 (2013)

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## The fundamentals: hydrodynamics

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## ${\bf Continuous\ representation\ (hydrodynamics)}$

- All started with macroscopic thermodynamical quantities: the properties of the system **as a whole**, the largest possible scale.
- Describing the system at smaller scales: the properties become **fields** changing in **time**:

 $\rho(\mathbf{x},t), \mathbf{u}(\mathbf{x},t), T(\mathbf{x},t).$ 

- ${\bf x}$  is the Euclidean 3D space.
- The equations of motion are the FD equations.
- The solution is the values of the fields at each location in space at every instant of time:  $\rho(\mathbf{x}, t), \mathbf{u}(\mathbf{x}, t), T(\mathbf{x}, t)$ .



## The fundamentals: atomistic

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## Atomistic representation

- The variables are the positions and momenta of the point masses, the atoms:

$$\{\mathbf{q}_1,\ldots,\mathbf{q}_N,\mathbf{p}_1,\ldots,\mathbf{p}_N\}$$

- The space is the 6N-dimensional phase space.
- The atoms interact through empirically (in MD) defined Hamiltonian $H({\bf q},{\bf p})$
- The equations of motion describing  $\mathbf{q}(t),\mathbf{p}(t)$  are the Hamilton equations

$$\frac{\mathrm{d}q_i(t)}{\mathrm{d}t} = \frac{\partial H(\mathbf{q},\mathbf{p})}{\partial p_i}, \frac{\mathrm{d}p_i(t)}{\mathrm{d}t} = -\frac{\partial H(\mathbf{q},\mathbf{p})}{\partial q_i}$$

- The solution is the molecular trajectory: the values of the coordinates and momenta at every moment of time:

$$\mathbf{q}(t), \mathbf{p}(t).$$



## Connecting the representations

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Calculating the continuous density:

$$\rho_q(\mathbf{q}; \mathbf{x}, t) = \sum_{j=1}^N m\delta(\mathbf{q}_i(t) - \mathbf{x})$$

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It is a *function of the molecular coordinates* (phase space variable), which also parametrically depends on  $\mathbf{x}$  and t.



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How the measurement is done: a probe of volume  $\Delta x$  is placed at the point **x** for a period of time  $\Delta t$  at time t.

The 'true' (measured) value of  $\rho(\mathbf{x}, t)$  is obtained by overaging  $\rho_q(\mathbf{q}; \mathbf{x}, t)$  over  $\Delta x$  and  $\Delta t$ .

$$\rho(\mathbf{x},t) = \langle \rho_q(\mathbf{q};\mathbf{x},t) \rangle_{\Delta x,\Delta t}$$

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## This is MD $\rightarrow$ HD transformation.

HD→MD - ???



## Describing fluctuations of the continuum

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The Landau-Lifshitz Fluctuating Hydrodynamics (LL-FH) equations are a generalisation of the deterministic Navier-Stokes (NS) equations:

$$\begin{split} &\frac{\partial\rho}{\partial t} + \nabla(\rho \mathbf{u}) = 0, \\ &\frac{\partial\rho u_i}{\partial t} + \nabla(\rho u_i \mathbf{u}) = \nabla_j \left( \Pi_{ij} + \tilde{\Pi}_{ij} \right), \\ &\frac{\partial\rho E}{\partial t} + \nabla(\rho E \mathbf{u}) = \nabla_j \left[ \left( \Pi_{ij} + \tilde{\Pi}_{ij} \right) \cdot u_i \right] + \nabla(\mathbf{q} + \tilde{\mathbf{q}}). \end{split}$$

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## Describing fluctuations of the continuum

The stress tensor consists of a deterministic part

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## $\Pi_{ij} = -(p - \eta_V \nabla \mathbf{u}) \,\delta_{ij} +$ $\eta \left( \partial_i u_i + \partial_j u_i - 2D^{-1} \nabla \mathbf{u} \cdot \delta_{ij} \right)$

and a stochastic part, a random Gaussian matrix with zero mean and the covariance

$$\begin{split} \langle \tilde{\Pi}_{ij}(r_1, t_1) \cdot \tilde{\Pi}_{kl}(r_2, t_2) \rangle &= \\ 2k_B T \bigg[ \eta \left( \delta_{ij} \delta_{ik} + \delta_{ik} \delta_{jl} \right) + \\ \left( \eta_V - \frac{2}{3} \eta \right) \delta_{ij} \delta_{jk} \bigg] \delta(r_1 - r_2) \delta(t_1 - t_2). \end{split}$$

This form of correlations follows from the fluctuation-dissipation theorem, which relates the thermal fluctuations to temperature.



## Describing fluctuations of the continuum

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The heat flow is also a sum of the averaged flow

$$q_i = \kappa \cdot \partial_i T$$

and a stochastic component with zero mean and the covariance

$$\langle \tilde{q}_i(r_1, t_1) \cdot \tilde{q}_j(r_2, t_2) \rangle = 2k_B \kappa T^2 \delta_{ij} \delta(r_1 - r_2) \delta(t_1 - t_2)$$

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$$\begin{split} \tilde{\Pi}_{ij} &= \sqrt{\frac{2k_BT}{\Delta x \Delta t}} \left( \sqrt{2\eta} \cdot \mathbf{G}_{ij}^s + \sqrt{D\eta_V} \frac{tr[\mathbf{G}]}{D} \mathbf{E}_{ij} \right) \\ \tilde{q}_i &= \sqrt{\frac{2k_B \kappa T^2}{\Delta x \Delta t}} \mathbf{G}_i \end{split}$$

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## Biomolecular scales





## Quick digression: hardware

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## RIKEN **K-computer**: 10Pflops, 640000 nodes scaling:



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## Hardware

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## $\mathbf{MDGRAPE-4:}\ 100\ \mathrm{ps}\ \mathrm{per}\ \mathrm{day}\ \mathrm{for}\ \mathrm{a}\ 100\mathrm{K}\ \mathrm{atoms}\ \mathrm{system}$





## Biomolecular scales





## Scales coupling: acyclic 'bottom-up'



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## Scales coupling: acyclic 'top-down'





## Scales coupling: cyclic





# An example of acyclic 'top-down' approach

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# $\frac{dx_{ip}}{dt} = u_{ip} + s \left( \frac{\sum_{N} m_{ip}}{M_{CFD}} u_i - \frac{\sum_{N} m_{ip} u_{ip}}{\sum_{N} m_{ip}} \right),$ $\frac{d}{dt} u_{ip}^{Newton} = \frac{F_{ip}}{m}$

- CFD = Deterministic N-S model

O'Connell Thompson (1995):

- Application of repulsive barrier to retain particles
- Not necessarily conserves macroscopic momentum balance

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- Not fully coupled (no feedback from MD to CFD)

see our poster for our version of 'top-down' coupling



## Our framework



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- The end domains HD and MD are described by purely hydrodynamic and purely Newtonian equations of motion respectively.
- In the hybrid domain the fluid consists of two "phases":
  - HD phase is a continuum water with volume fraction  $s = \frac{V_1}{V}$ ,
  - MD phase is a phase that incorporates atoms, its volume fraction is (1 s).
- The parameter s = s(x) is the function of space coordinates, such that s = 1 in the HD domain, s = 0 in the MD domain.



## Mass conservation

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### For HD phase:

$$\frac{\partial}{\partial t}\left(s\rho\right) + \frac{\partial}{\partial x_{i}}\left(u_{i}s\rho\right) = J,$$

### For MD phase:

$$\frac{\partial}{\partial t}\left((1-s)\sum_{p=1,N(t)}\rho_p\right) + \frac{\partial}{\partial x_i}\left((1-s)\sum_{p=1,N(t)}\rho_p u_{ip}\right) = -J,$$

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where  $\rho_p = m_p/V$  is the density of MD particles and J is the birth/death rate due to the coupling between the phases.

$$\tilde{\rho} = s\rho + (1-s)\sum_{p=1,N(t)}\rho_p$$



## Conservation of momentum

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$$\frac{\partial}{\partial t}\left(su_{i}\rho\right) + \frac{\partial}{\partial x_{j}}\left(u_{j}u_{i}s\rho\right) = sF_{i} + J_{2},$$

where  $J_2$  is the HD-MD interaction force and  $F_i$  is the hydrodynamic force.

## For MD phase:

For HD phase:

$$\frac{\partial}{\partial t} \left( (1-s) \sum_{p=1,N(t)} u_{i,p} \rho_p \right) + \frac{\partial}{\partial x_j} \left( (1-s) \sum_{p=1,N(t)} \rho_p u_{i,p} u_{j,p} \right)$$
$$= (1-s) \sum_{p=1,N(t)} F_{i,p} - J_2$$

$$\tilde{\rho}\tilde{u}_j = \left[s\rho u_j + (1-s)\sum_{p=1,N(t)}\rho_p u_{jp}\right]$$

QC



## Restricted dynamics

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The deviations of  $\tilde{\rho}$  are driven towards the correct value  $\sum_{p=1,N(t)} \rho_p$ :

$$\frac{D}{Dt_0} \left( \tilde{\rho} - \sum_{p=1,N(t)} \rho_p \right) = L^{(\rho)} \cdot \left( \tilde{\rho} - \sum_{p=1,N(t)} \rho_p \right),$$

where 
$$\frac{D}{Dt_0} \cdot = \frac{\partial}{\partial t} \cdot + \nabla(\mathbf{u} \cdot),$$

and similarly for  $\tilde{u}_j \tilde{\rho}$ :

$$\frac{D}{Dt_0} \left( \tilde{u}_j \tilde{\rho} - \sum_{p=1,N(t)} u_{jp} \rho_p \right) = L^{(u)} \cdot \left( \tilde{u}_j \tilde{\rho} - \sum_{p=1,N(t)} u_{jp} \rho_p \right) \\ + s \nabla_j \left( \Pi_{ij} + \tilde{\Pi}_{ij} \right).$$

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## Restricted dynamics

 $\tilde{\rho}$  is diffused towards  $\sum_{p=1,N(t)} \rho_p$ :

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$$L^{(\rho)} \cdot \left( \tilde{\rho} - \sum_{p=1,N(t)} \rho_p \right) = \frac{\partial}{\partial x_i} \left( s(1-s)\alpha \frac{\partial}{\partial x_i} \left( \tilde{\rho} - \sum_{p=1,N(t)} \rho_p \right) \right).$$

 $\tilde{u}_j \tilde{\rho}$  is diffused towards  $\sum_{p=1,N(t)} u_{jp} \rho_p$ :

$$L^{(u)} \cdot \left( \tilde{u}_{j} \tilde{\rho} - \sum_{p=1,N(t)} u_{jp} \rho_{p} \right) = \frac{\partial}{\partial x_{i}} \left( s(1-s)\beta \frac{\partial}{\partial x_{i}} \left( \tilde{u}_{j} \tilde{\rho} - \sum_{p=1,N(t)} u_{jp} \rho_{p} \right) \right).$$

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## The sources J and $J_2$

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From these constrains the sources J and  $J_2$  can be found:

$$\begin{split} J &= s \frac{\partial}{\partial t} \sum_{p=1,N(t)} \rho_p + \frac{\partial}{\partial x_i} \left( s u_i \sum_{p=1,N(t)} \rho_p \right) + \\ & \frac{\partial}{\partial x_i} \left( s(1-s) \alpha \frac{\partial}{\partial x_i} \left( \tilde{\rho} - \sum_{p=1,N(t)} \rho_p \right) \right), \end{split}$$

$$J_{2} = s \frac{\partial}{\partial t} \sum_{p=1,N(t)} \rho_{p} u_{jp} + \frac{\partial}{\partial x_{i}} \left( su_{i} \sum_{p=1,N(t)} \rho_{p} u_{jp} \right) - sF_{j} + \frac{\partial}{\partial x_{i}} \left( s(1-s)\beta \frac{\partial}{\partial x_{i}} \left( \tilde{u}_{j}\tilde{\rho} - \sum_{p=1,N(t)} u_{jp}\rho_{p} \right) \right),$$



## Modified MD equations

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For known J and  $J_2$  MD equations are modified to preserve macroscopic conservation laws:

$$\frac{dx_{ip}}{dt} = u_{ip} + s(u_i - u_{ip}) + s(1 - s)\alpha \frac{\partial}{\partial x_i} \left(\tilde{\rho} - \sum_{p=1,N(t)} \rho_p\right) \frac{1}{\rho_p N(t)}$$

$$\frac{du_{jp}}{dt} = (1-s)F_{jp}/\rho_p + sF_j/\rho_p/N(t) 
+ \frac{\partial}{\partial x_i} \left( s(1-s)\alpha \sum_{p=1,N(t)} u_{jp}/N(t) \frac{\partial}{\partial x_i} \left( \tilde{\rho} - \sum_{p=1,N(t)} \rho_p \right) \right) \frac{1}{\rho_p N(t)} 
- \frac{\partial}{\partial x_i} \left( s(1-s)\beta \frac{\partial}{\partial x_i} \left( \tilde{u}_j \tilde{\rho} - \sum_{p=1,N(t)} u_{jp} \rho_p \right) \right) \frac{1}{\rho_p N(t)},$$



## Results: 2D Lennard-Jones liquid

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## Velocities at various s



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## Velocities at various s



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## Velocities at various s



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## Results: 3D Lennard-Jones liquid

### Hybrid MD/HD Convergence of fluctuations towards the same limit modelling 0.08 fields. atoms. 8 8 XHO 8 0.06 -MD 0 std(u'\_) FH 0 0.04 -MD, S = 0.8Δ FH. S = 0.8 V $\overline{ux}$ . S = 0.8 0 3D liquid 0.02 -0 Ó 10000 20000 30000 40000 **MD** iterations

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## Results: 3D Lennard-Jones liquid

### Hybrid MD/HD modelling

## Convergence of fluctuations towards the same limit

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## Conclusions

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- Atomistic and continuum representations of liquid can be connected without artificial barriers or ad hoc correction forces in space and time.
- The domains of each representation can be defined arbitrarily in space and time.

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- Challenges: *multiphysics* (non-stationary MD + hydrodynamics), multiscale *computing* (efficient multi space-time algorithms in parallel environment).



## Thoughts for the future

### Hybrid MD/HD modelling

### Introduction

The background

fields, atoms, scales, etc...

hydrodynami

Coupling the scales

The model

Conservation laws

Constraining the dynamics

Results

2D Lennard-Jones 3D liquid

Conclusions

The need to organize activities in multiscale modelling:

- a database of existing well documented algorithms and codes in multiscale modelling;
- optimising existing algorithms for computational efficiency (GPU, parallel scalability, distributed computing, etc);
- a database of benchmark cases (from the simplest molecular models to realistic biomolecular systems);
- training: hands-on workshops, schools on existing software.